

Searching Paths of Constant Bandwidth

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Abstract

As a generalization of paths, the notion of paths of bandwidth w is introduced. We show that, for constant $w \geq 1$, the corresponding search problem for such a path of length k in a given graph is NP-complete and fixed-parameter tractable in the parameter k , like this is known for the special case $w = 1$, the LONGEST PATH problem. We state the FPT algorithm in terms of a guess and check protocol which uses witnesses of size polynomial in the parameter.

1 Introduction

A *path* within a graph is one of the most elementary notions of graph theory and its applications. The LONGEST PATH is the computational problem which asks for a given graph G and an integer k whether there is a path of length k in G which is simple, i.e. all vertices are different from each other. The LONGEST PATH is NP-complete [GJ97]. Moreover, the LONGEST PATH problem is fixed-parameter tractable in the parameter k . This was shown by Monien [Mo85] and improved with respect to running time by Alon, Yuster, Zwick [AYZ95], using randomization techniques.

In this paper we generalize the notion of a path: a path of bandwidth w , or short w -path, in a graph G is a sequence (v_1, \dots, v_n) of vertices such that for all v_i, v_j with $1 \leq j - i \leq w$ the pair (v_i, v_j) is an edge in G , see Fig. 1 for an example of a 2-path. 1-paths are paths in the usual sense. It will be easy to show that for every $w \geq 1$ the corresponding computational problem BANDWIDTH- w -PATH, which asks for a given graph G and an integers k whether there exists a simple w -path of length k in G , is NP-complete.

The BANDWIDTH- w -PATH problem for every w is fixed-parameter tractable in the parameter k , this will be shown according to the characterization of $\text{FPT} \cap \text{NP}$ by Cai, Chen, Downey & Fellows [CCDF95] via an “FPT guess and check protocol” using witnesses of size only dependent on the parameter. The runtime obtained for our guess and check protocol, for the case $w = 1$, which is the LONGEST PATH problem, and seen as a deterministic exhaustive search algorithm, is worse than the algorithms of Monien [Mo85] and Alon, Yuster, Zwick [AYZ95]. On the other hand, our algorithm is more easily stated and can immediately be applied to the BANDWIDTH- w -PATH problem. Moreover, the algorithms of [Mo85, AYZ95] do not seem to give better FPT guess and check protocols.

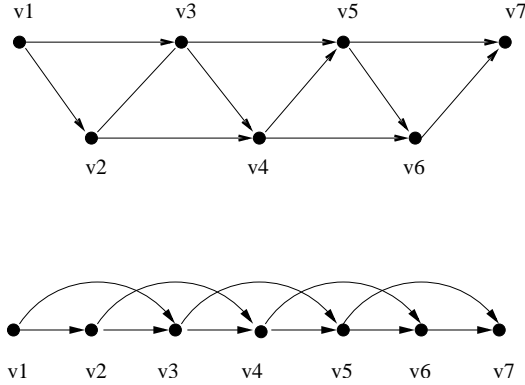


Figure 1: Two drawings of the same 2-path of length 5, vertex-disjoint and deterministic

2 Paths of constant bandwidth

Let G be a digraph and let $w, k \geq 1$. A *path of bandwidth w and length k* in G is a sequence of $k + w$ vertices (v_1, \dots, v_{k+w}) such that the pair (v_i, v_{i+j}) is an edge of G for every i with $1 \leq i \leq k$ and every j with $1 \leq j \leq w$. A path of bandwidth w and length k will also be called *w -path of length k* or, even shorter, *(w, k) -path*. A 1-path of length k is a path of length k in the usual sense. (For a path of length k some authors count the number of vertices while others count the number of edges – what is one less. In this paper we count the number of edges.) In Figures 1, 2, and 3 some 2-paths and 3-paths are shown. Note that a $(w, 1)$ -path is a $(w + 1)$ -clique: every two nodes are connected by an edge. A (w, k) -path can actually be seen as a sequence of k $(w + 1)$ -cliques with two subsequent cliques “glued” together by their common w elements.

A (w, k) -path (v_1, \dots, v_{k+w}) is *vertex-disjoint* if all v_i are different from each other, it is *simple* if all w -tuples $(v_1, \dots, v_w), (v_2, \dots, v_{w+1}), \dots, (v_k, \dots, v_{k+w})$ are different from each other. A vertex-disjoint (k, n) -path is simple, but not vice versa for $k \geq 2$, see Figure 3. A vertex-disjoint (w, k) -path, as a graph on its own, is the graph with $k + w$ vertices having bandwidth w and a maximal set of edges, that is why we choose the name “bandwidth” for the number w (see [PT99, GJ97] for the definition of bandwidth of a graph).

Though the notion of w -paths within a graph G is a rather natural generalization of paths the authors could not find references for it in the literature. The closest concept found is the *w -ray* from Proskurowski & Telle [PT99], corresponding to a vertex-disjoint w -path (as a graph on its own).

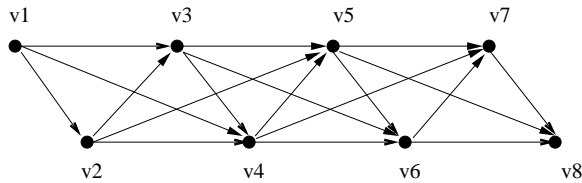


Figure 2: A 3-path of length 5, vertex-disjoint and deterministic

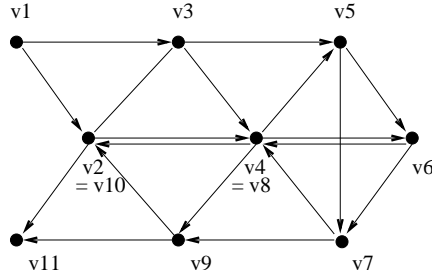


Figure 3: A 2-path of length 10, deterministic and simple but not vertex-disjoint

A (w, k) -path (v_1, \dots, v_{k+w}) is *deterministic in G* if for every $1 \leq i \leq k$ v_{i+w} is the only vertex in the graph G having the property that all edges $(v_i, v_{i+w}), \dots, (v_{i+w-1}, v_{i+w})$ are edges of the graph. For example, a deterministic 1-path has the property that every vertex of it – besides the last one – has exactly one outgoing edge in G .

For $w < k$, a (w, k) -path (v_1, \dots, v_{k+w}) is a *cycle of bandwidth w and length k* , short w -cycle of length k or (w, k) -cycle, if $(v_{k+1}, \dots, v_{k+w}) = (v_1, \dots, v_w)$. The cycle is *vertex-disjoint* if v_1, \dots, v_k are different from each other, it is *simple* if (v_1, \dots, v_{k+w-1}) is a simple w -path, see Fig. 4 for an example.

For undirected graphs the definitions can be transferred literally.

For a fixed w let BANDWIDTH- w -PATH be the set of pairs $\langle G, k \rangle$ such that the digraph G contains a simple (w, k) -path. BANDWIDTH-1-PATH = LONGEST-PATH. Let BANDWIDTH-PATH be the double-parameterized problem consisting of the triples $\langle G, w, k \rangle$ such that the digraph G contains a simple (w, k) -path.

Some variations of these problems: Let the prefixes UNDIRECTED- and DISJOINT- in front of these problem names indicate that the input graph is undirected, or, independently, that the path to be found has to be not only simple but vertex-disjoint, respectively. Let CYCLE instead of PATH in a problem name denote that the path to be found has to be a cycle. Call these further 7 problems the *variations* of the BANDWIDTH- w -PATH, resp. BANDWIDTH-PATH, problem.

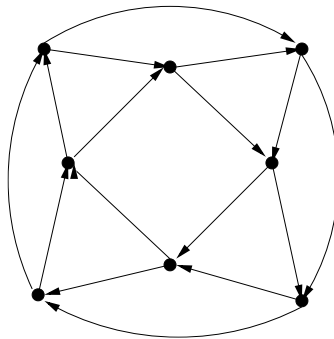


Figure 4: A 2-cycle of length 8, deterministic and vertex-disjoint

Proposition 1 (a) BANDWIDTH-PATH is NP-complete, likewise its variations.
(b) For every $w \geq 1$ the problem BANDWIDTH-w-PATH is NP-complete, likewise its variations.

Proof. Obviously all problems are in NP. BANDWIDTH-PATH is NP-complete because LONGEST PATH is a subproblem. In order to show NP-completeness of BANDWIDTH-w-PATH we reduce LONGEST PATH to it. Let some directed graph G be given. Let the graph $\phi(G)$ consist of w copies G_1, \dots, G_w of G , and let an edge from u in G_i to v in G_j only exist if $i < j$ and in G there is a simple path of length $j - i$ from u to v . It holds: G has a simple path of length k iff $\phi(G)$ has a simple w -path of length k . **q.e.d.**

We mention that for fixed w the problem of searching for a *deterministic* simple w -path of a given length k can be done in PTIME by a straightforward marking algorithm.

3 Fixed-Parameter Tractability

The following notion is from Downey & Fellows [DF92] though it can already be found – without giving it a name – in Monien [Mo85][p. 240, the two paragraphs before and after Th. 1, resp.].

Definition 1 (fixed-parameter tractability [Mo85, DF92]) A computational problem consisting of pairs $\langle x, k \rangle$ is fixed-parameter tractable in the parameter k if there is a deciding algorithm for it having run-time $f(k) \cdot |x|^c$ for some recursive function f and some constant c .

We use the following characterization of $\text{FPT} \cap \text{NP}$ by Cai, Chen, Downey & Fellows [CCDF95]:

Theorem 1 (Cai et al. [CCDF95]) A language $L \in \text{NP}$ consisting of pairs $\langle x, k \rangle$ is fixed-parameter tractable in the parameter k iff there exists a recursive function $s(k)$ and a PTIME computable language C such that $\langle x, k \rangle \in L \iff \exists y \leq s(k) : \langle x, k, y \rangle \in C$.

We call the function s the *witness size function*, and the language C the *witness checker*, and we say that these two together form an FPT *guess and check protocol* for L .

Theorem 2 For every $w \geq 1$ the problem BANDWIDTH-w-PATH is fixed parameter tractable in the parameter k , likewise its variations. More specifically, there exists an FPT guess and check protocol for it with a witness size function $s(k) = \binom{k}{2} \cdot \log k$ and a witness checker having runtime $O(w \cdot k^2 \cdot |E|^w \cdot |V|^w)$.

Proof. We first consider the case $w = 1$, i.e. the LONGEST PATH problem. Afterwards we will see that the algorithm is generalizable to the BANDWIDTH-w-PATH problem for $w > 1$. We state an FPT guess and check protocol for LONGEST PATH with the witness size function $s(k) = \binom{k}{2} \cdot \log k$ and a witness checker with runtime $O(k^2 \cdot |E| \cdot |V|)$.

Let a digraph G with n vertices be given. We want to find out whether the graph contains a simple path $p = (v_1, \dots, v_{k+1})$ of length k . We will work with *witnesses*. The intention of a witness is to tell the algorithm in the moment when it is trying to build an initial segment (v_1, \dots, v_i) of the simple path of length k which are the future vertices v_{i+1}, \dots, v_{k+1} of the simple path – so that the algorithm does not pick one of these future vertices as a part of the initial segment. Unfortunately,

$a_{2,1}$	$a_{2,2}$	$a_{2,3}$	$a_{2,4}$	= a_2 =	1	1	0	0
$a_{3,1}$	$a_{3,2}$	$a_{2,3}$		= a_3 =	1	2	0	
$a_{4,1}$	$a_{4,2}$			= a_4 =	2	0		
$a_{5,1}$				= a_5 =	0			

Figure 5: Witness table for a simple path of length 4

we cannot use the tuple (v_1, \dots, v_{k+1}) as a witness, because that way we would have n^{k+1} potential witnesses, so that we would need at least $(k+1) \log(n)$ bits to encode them, a number growing in n . But for the FPT guess and check protocol we need some witness size function $s(k)$ only dependent on k .

We choose the following kind of witnesses. A *witness* for such a simple path of length k consists of $k(k+1)/2 = \binom{k+1}{2}$ numbers $a_{i,j} \in \{0, 1, \dots, k\}$, for $2 \leq i \leq k+1$ and $j \in \{1, \dots, k-i+2\}$. The witness can be visualized as a half-matrix a , see Figure 5. Let a_i for $2 \leq i \leq k+1$ be the tuple $(a_{i,1}, \dots, a_{i,k-i+2})$. We can restrict the witnesses to have these properties: a_i contains only numbers $\leq i-1$ and at least one 0. There is some redundancy, for example $a_{k+1,1}$ will always be 0. Nevertheless, the order of magnitude of the witness size function $s(k)$ does not seem to be improvable by these “little savings”.

For every witness a the main algorithm C does the following: In every of the k steps $i = 2, 3, \dots, k+1$ it computes for every vertex v a value $f_{a,i}(v)$, defined further below, which is either a vertex or has the value **nil** (standing for “not existing”), and stores this function for use in the following steps. The following pseudo code shows the main structure of the algorithm.

Main algorithm C

Input: graph G , number $k \leq |G|$, and a witness a

for every vertex v set $f_{a,1}(v) := v$;

for $i = 2, \dots, k+1$ do

for every vertex v in G do

compute $f_{a,i}(v)$ and store it;

if $i = k+1$ and $f_{a,i}(v) \neq \mathbf{nil}$ ACCEPT and STOP;

REJECT and STOP;

The computation of the value $f_{a,i}(v)$ – which is either **nil** or a vertex – is described in the pseudo code below. Assume w.l.o.g. that for each vertex there is a list of incoming edges (ending with the **nil** list element) in which the edges appear according to the order on the vertices. As a useful

abbreviation let $f_{a,i}^d(v)$ for a vertex v and d with $1 \leq d \leq i + 1$ be defined via

$$f_{a,i}^1(v) := v, \quad f_{a,i}^2(v) := f_{a,i}(v), \quad \text{and} \quad f_{a,i}^{d+1}(v) := f_{a,i-1}^d(f_{a,i}(v))$$

with this value being **nil** in case $f_{a,i}(v)$ or $f_{a,i-1}^d(f_{a,i}(v))$ equals **nil**. Intuitively, $f_{a,i}^d(v)$ follows – starting in v – for growing $d = 1, \dots, i + 1$ the “backward path” given by the $f_{a,i-d}$ -functions, see Figure 6. The upper index d numbers the vertices of this path, and the witness elements $a_{i,j} \geq 0$ will refer to this numbering.

By easy induction on i , the following invariant will be guaranteed for every witness a , every i with $2 \leq i \leq k + 1$, and every vertex v :

(Inv1) If $f_{a,i}(v) \neq \mathbf{nil}$ then the “backward path” $(f_{a,i}^i(v), \dots, f_{a,i}^2(v), f_{a,i}^1(v))$ is a simple path of length $i - 1$.

Computing $f_{a,i}(v)$

```

Input:  $i, a$ , and  $v$ . Already computed:  $f_{a,1}, \dots, f_{a,i-1}$ .
set  $F := \{v\}$ ;
set  $j := 1$ ;
if there are no incoming edges for  $v$  set  $f_{a,i}(v) := \mathbf{nil}$  and STOP;
set  $e = (u, v)$  to be the first edge incoming to  $v$ ;
while  $e \neq \mathbf{nil}$  do
  if  $f_{a,i-1}(u) \neq \mathbf{nil}$  and none of the vertices  $f_{a,i-1}^1(u), f_{a,i-1}^2(u), \dots, f_{a,i-1}^i(u)$  is in  $F$  do
    set  $c := a_{i,j}$ ;
    if  $c = 0$ 
      set  $f_{a,i}(v) := u$  and STOP;
    otherwise
      set  $F := F \cup \{f_{a,i}^c(u)\}$ ;
      set  $j := j + 1$ ;
  set  $e = (u, v) := \text{next edge going into } v$ ;
set  $f_{a,i}(v) := \mathbf{nil}$  and STOP;

```

Verification of the main algorithm C : If the algorithm accepts then it has found for this witness a a vertex v such that $f_{a,k+1}(v) \neq \mathbf{nil}$. By invariant (Inv1), case $i = k + 1$, the backward path starting in v is a simple path of length k .

On the other hand assume that there is a simple path of length k in G . Let $s = (s_1, \dots, s_{k+1})$ be the lexicographically smallest among them (largest weight on s_{k+1} , unlike, for example, with decimal numbers). With the knowledge of this path and its vertices we will construct a witness b such that the main algorithm will accept for witness b .

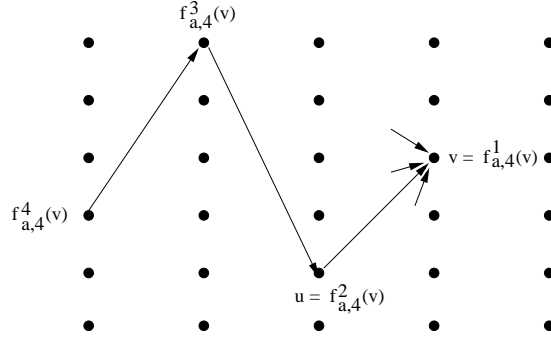


Figure 6: A “backward path”, starting in v

Constructing b

Input: s_1, \dots, s_{k+1} .

for every vertex v set $f_{b_1,1}(v) = v$;

for $i = 2$ to $k + 1$ do

 set $e = (u, s_i) :=$ first edge going into s_i ;

 set $F = \{s_i\}$;

 set $j := 1$;

 repeat

 while $f_{b_{i-1},i-1}(u) = \mathbf{nil}$ or some of the vertices $f_{b_{i-1},i-1}^1(u), \dots, f_{b_{i-1},i-1}^i(u)$ is in F

 set $e = (u, s_i) :=$ next edge going into s_i ;

 if there is a $c \in \{1, \dots, i\}$ such that $f_{b_{i-1},i-1}^c(u) \in \{s_{i+2}, \dots, s_{k+1}\}$

 set $b_{i,j} := c$ for the smallest such c ;

 set $F := F \cup \{f_{b_{i-1},i-1}^c(u)\}$;

 set $j := j + 1$;

 until there is no such c ;

$b_{i,j} := 0$

 compute $f_{b_i,i}(v)$ for all vertices v ;

The crucial invariant kept by this construction is the following:

(Inv2) For every i with $2 \leq i \leq k + 1$ it holds: $f_{b_i,i}(s_i) = s_{i-1}$.

The invariant holds via induction on i : the construction of b_i prevents $f_{b_i,i}(s_i)$ from choosing one of the vertices s_{i+1}, \dots, s_{k+1} which will be needed in the future but which would be – without

the witness – unknown at step i . Because there are at most $k - i + 1$ such vertices the repeat loop will always terminate and, moreover, the part b_i of the witness has sufficient size. For every $2 \leq i \leq k + 1$ it is guaranteed that the computation of $f_{b,i}(s_i)$ will terminate, i.e. will be not-**nil**, because at least (s_{i-1}, s_i) is a suitable edge, and this will be the first suitable edge which $f_{b,i}(s_i)$ will find, i.e. $f_{b,i}(s_i) = s_{i-1}$, because otherwise $s = (s_1, \dots, s_{k+1})$ would not be lexicographically minimal.

Invariant (Inv2) implies for $i = k + 1$ that the back path $(f_{b,k+1}^{k+1}(s_{k+1}), \dots, f_{b,k+1}^2(s_{k+1}), f_{b,k+1}^1(s_{k+1}))$ at s_{k+1} equals $s = (s_1, \dots, s_{k+1})$, i.e. the main algorithm C will accept the input graph for this witness b via a non-**nil** value of $f_{b,k+1}$ at vertex s_{k+1} . This finishes the correctness proof for the FPT guess and check protocol.

The running time of all $f_{a_i}(v)$ for a fixed i is $O(k \cdot |E|)$ (we ignore some $\log(k)$ factors for the comparison algorithms). Therefore, the main algorithm C has runtime $O(k^2 \cdot |V| \cdot |E|)$. Representing all witnesses can be done with $\binom{k}{2} \cdot \log k$ bits, i.e. the witness size function can be chosen this way (note that the diagonal of the half matrix does not need to be stored – it can be assumed to consist of 0's). This finishes the proof that an FPT guess and check protocol exists for LONGEST PATH.

Cases $w > 1$. We first do a graph transformation. From the given graph G construct the following graph G' : Consider all w -tuples (v_1, \dots, v_w) of vertices of G . Make such a tuple a vertex of G' if the tuple represents a directed w -clique in G , i.e. (v_i, v_j) is an edge in G for $1 \leq i < j \leq w$. The edges in G' are defined to consist of the pairs of such w -cliques of the special form $((v_1, \dots, v_w), (v_2, \dots, v_w, v_{w+1}))$ such that also (v_1, v_{w+1}) is an edge in G . We have the property: G contains a simple w -path of length k iff G' contains a 1-path of length k . The witness checker consists therefore of this graph transformation and subsequently the checking algorithm C for $w = 1$ running on G' . In total the checking takes $O(w \cdot |V|^w \cdot |E|^w)$ time, the first w stems from a slightly higher comparison time for tuples. The witnesses size function does not change.

Variants: For the vertex disjoint case with $w > 1$ it is not enough to do the graph transformation, one has to go inside the checking algorithm C and maintain the vertex lists appropriately. **q.e.d.**

It should be mentioned that, when given k as a constant, the problem whether a given graph has a (w, k) -path does not seem to be fixed-parameter tractable in the parameter w because the W[1]-complete CLIQUE problem is obviously reducible to it, see for example [CCDF95] for the definition of W[1].

4 Conclusions and Open Questions

We introduced for every $w \geq 1$ the NP-complete problem BANDWIDTH- w -PATH and showed that it is fixed-parameter tractable in the length parameter k by presenting an FPT guess and check protocol for it, according to the characterization of Cai et al. [CCDF95].

As an open problem we suggest to study whether the witness size function, especially for the case LONGEST PATH, can be improved from the quasi-quadratic function $\binom{k}{2} \log k$ to some quasi-linear function, for example by the methods of Monien [Mo85] or Alon, Yuster & Zwick [AYZ95].

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