

# Searching Paths of Constant Bandwidth

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WSI-2004-10

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ISSN 0946-3852



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## Abstract

As a generalization of paths, the notion of paths of bandwidth  $w$  is introduced. We show that, for constant  $w \geq 1$ , the corresponding search problem for such a path of length  $k$  in a given graph is NP-complete and fixed-parameter tractable in the parameter  $k$ , like this is known for the special case  $w = 1$ , the LONGEST PATH problem. We state the FPT algorithm in terms of a guess and check protocol which uses witnesses of size polynomial in the parameter.

## 1 Introduction

A *path* within a graph is one of the most elementary notions of graph theory and its applications. The LONGEST PATH is the computational problem which asks for a given graph  $G$  and an integer  $k$  whether there is a path of length  $k$  in  $G$  which is simple, i.e. all vertices are different from each other. The LONGEST PATH is NP-complete [GJ97]. Moreover, the LONGEST PATH problem is fixed-parameter tractable in the parameter  $k$ . This was shown by Monien [Mo85] and improved with respect to running time by Alon, Yuster, Zwick [AYZ95], using randomization techniques.

In this paper we generalize the notion of a path: a path of bandwidth  $w$ , or short  $w$ -path, in a graph  $G$  is a sequence  $(v_1, \dots, v_n)$  of vertices such that for all  $v_i, v_j$  with  $1 \leq j - i \leq w$  the pair  $(v_i, v_j)$  is an edge in  $G$ , see Fig. 1 for an example of a 2-path. 1-paths are paths in the usual sense. It will be easy to show that for every  $w \geq 1$  the corresponding computational problem BANDWIDTH- $w$ -PATH, which asks for a given graph  $G$  and an integers  $k$  whether there exists a simple  $w$ -path of length  $k$  in  $G$ , is NP-complete.

The BANDWIDTH- $w$ -PATH problem for every  $w$  is fixed-parameter tractable in the parameter  $k$ , this will be shown according to the characterization of  $\text{FPT} \cap \text{NP}$  by Cai, Chen, Downey & Fellows [CCDF95] via an “FPT guess and check protocol” using witnesses of size only dependent on the parameter. The runtime obtained for our guess and check protocol, for the case  $w = 1$ , which is the LONGEST PATH problem, and seen as a deterministic exhaustive search algorithm, is worse than the algorithms of Monien [Mo85] and Alon, Yuster, Zwick [AYZ95]. On the other hand, our algorithm is more easily stated and can immediately be applied to the BANDWIDTH- $w$ -PATH problem. Moreover, the algorithms of [Mo85, AYZ95] do not seem to give better FPT guess and check protocols.

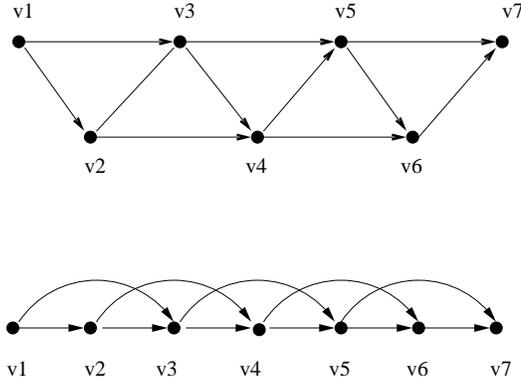


Figure 1: Two drawings of the same 2-path of length 5, vertex-disjoint and deterministic

## 2 Paths of constant bandwidth

Let  $G$  be a digraph and let  $w, k \geq 1$ . A *path of bandwidth  $w$  and length  $k$*  in  $G$  is a sequence of  $k + w$  vertices  $(v_1, \dots, v_{k+w})$  such that the pair  $(v_i, v_{i+j})$  is an edge of  $G$  for every  $i$  with  $1 \leq i \leq k$  and every  $j$  with  $1 \leq j \leq w$ . A path of bandwidth  $w$  and length  $k$  will also be called  *$w$ -path of length  $k$*  or, even shorter,  *$(w, k)$ -path*. A 1-path of length  $k$  is a path of length  $k$  in the usual sense. (For a path of length  $k$  some authors count the number of vertices while others count the number of edges – what is one less. In this paper we count the number of edges.) In Figures 1, 2, and 3 some 2-paths and 3-paths are shown. Note that a  $(w, 1)$ -path is a  $(w + 1)$ -clique: every two nodes are connected by an edge. A  $(w, k)$ -path can actually be seen as a sequence of  $k$   $(w + 1)$ -cliques with two subsequent cliques “glued” together by their common  $w$  elements.

A  $(w, k)$ -path  $(v_1, \dots, v_{k+w})$  is *vertex-disjoint* if all  $v_i$  are different from each other, it is *simple* if all  $w$ -tuples  $(v_1, \dots, v_w), (v_2, \dots, v_{w+1}), \dots, (v_k, \dots, v_{k+w})$  are different from each other. A vertex-disjoint  $(k, n)$ -path is simple, but not vice versa for  $k \geq 2$ , see Figure 3. A vertex-disjoint  $(w, k)$ -path, as a graph on its own, is the graph with  $k + w$  vertices having bandwidth  $w$  and a maximal set of edges, that is why we choose the name “bandwidth” for the number  $w$  (see [PT99, GJ97] for the definition of bandwidth of a graph).

Though the notion of  $w$ -paths within a graph  $G$  is a rather natural generalization of paths the authors could not find references for it in the literature. The closest concept found is the  *$w$ -ray* from Proskurowski & Telle [PT99], corresponding to a vertex-disjoint  $w$ -path (as a graph on its own).

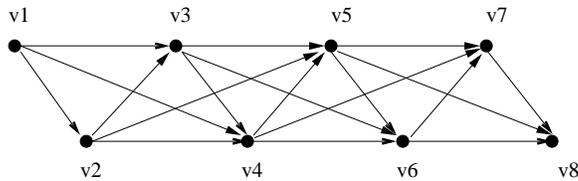


Figure 2: A 3-path of length 5, vertex-disjoint and deterministic

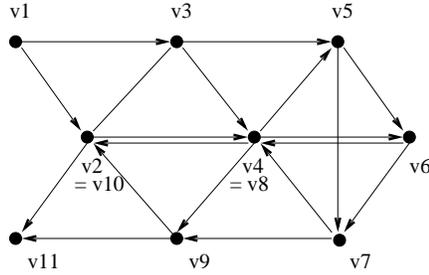


Figure 3: A 2-path of length 10, deterministic and simple but not vertex-disjoint

A  $(w, k)$ -path  $(v_1, \dots, v_{k+w})$  is *deterministic in  $G$*  if for every  $1 \leq i \leq k$   $v_{i+w}$  is the only vertex in the graph  $G$  having the property that all edges  $(v_i, v_{i+w}), \dots, (v_{i+w-1}, v_{i+w})$  are edges of the graph. For example, a deterministic 1-path has the property that every vertex of it – besides the last one – has exactly one outgoing edge in  $G$ .

For  $w < k$ , a  $(w, k)$ -path  $(v_1, \dots, v_{k+w})$  is a *cycle of bandwidth  $w$  and length  $k$* , short  $w$ -cycle of length  $k$  or  $(w, k)$ -cycle, if  $(v_{k+1}, \dots, v_{k+w}) = (v_1, \dots, v_w)$ . The cycle is *vertex-disjoint* if  $v_1, \dots, v_k$  are different from each other, it is *simple* if  $(v_1, \dots, v_{k+w-1})$  is a simple  $w$ -path, see Fig. 4 for an example.

For undirected graphs the definitions can be transferred literally.

For a fixed  $w$  let BANDWIDTH- $w$ -PATH be the set of pairs  $\langle G, k \rangle$  such that the digraph  $G$  contains a simple  $(w, k)$ -path. BANDWIDTH-1-PATH = LONGEST-PATH. Let BANDWIDTH-PATH be the double-parameterized problem consisting of the triples  $\langle G, w, k \rangle$  such that the digraph  $G$  contains a simple  $(w, k)$ -path.

Some variations of these problems: Let the prefixes UNDIRECTED- and DISJOINT- in front of these problem names indicate that the input graph is undirected, or, independently, that the path to be found has to be not only simple but vertex-disjoint, respectively. Let CYCLE instead of PATH in a problem name denote that the path to be found has to be a cycle. Call these further 7 problems the *variations* of the BANDWIDTH- $w$ -PATH, resp. BANDWIDTH-PATH, problem.

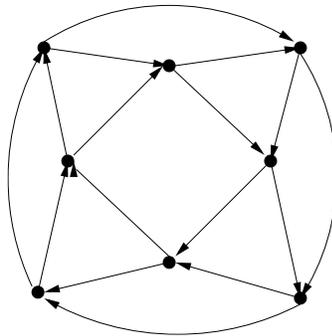


Figure 4: A 2-cycle of length 8, deterministic and vertex-disjoint

**Proposition 1** (a) BANDWIDTH-PATH is NP-complete, likewise its variations.  
 (b) For every  $w \geq 1$  the problem BANDWIDTH-w-PATH is NP-complete, likewise its variations.

**Proof.** Obviously all problems are in NP. BANDWIDTH-PATH is NP-complete because LONGEST PATH is a subproblem. In order to show NP-completeness of BANDWIDTH-w-PATH we reduce LONGEST PATH to it. Let some directed graph  $G$  be given. Let the graph  $\phi(G)$  consist of  $w$  copies  $G_1, \dots, G_w$  of  $G$ , and let an edge from  $u$  in  $G_i$  to  $v$  in  $G_j$  only exist if  $i < j$  and in  $G$  there is a simple path of length  $j - i$  from  $u$  to  $v$ . It holds:  $G$  has a simple path of length  $k$  iff  $\phi(G)$  has a simple  $w$ -path of length  $k$ . **q.e.d.**

We mention that for fixed  $w$  the problem of searching for a *deterministic* simple  $w$ -path of a given length  $k$  can be done in PTIME by a straightforward marking algorithm.

### 3 Fixed-Parameter Tractability

The following notion is from Downey & Fellows [DF92] though it can already be found – without giving it a name – in Monien [Mo85][p. 240, the two paragraphs before and after Th. 1, resp.].

**Definition 1 (fixed-parameter tractability [Mo85, DF92])** A computational problem consisting of pairs  $\langle x, k \rangle$  is fixed-parameter tractable in the parameter  $k$  if there is a deciding algorithm for it having run-time  $f(k) \cdot |x|^c$  for some recursive function  $f$  and some constant  $c$ .

We use the following characterization of  $\text{FPT} \cap \text{NP}$  by Cai, Chen, Downey & Fellows [CCDF95]:

**Theorem 1 (Cai et al. [CCDF95])** A language  $L \in \text{NP}$  consisting of pairs  $\langle x, k \rangle$  is fixed-parameter tractable in the parameter  $k$  iff there exists a recursive function  $s(k)$  and a PTIME computable language  $C$  such that  $\langle x, k \rangle \in L \iff \exists y \leq s(k) : \langle x, k, y \rangle \in C$ .

We call the function  $s$  the *witness size function*, and the language  $C$  the *witness checker*, and we say that these two together form an FPT *guess and check protocol* for  $L$ .

**Theorem 2** For every  $w \geq 1$  the problem BANDWIDTH-w-PATH is fixed parameter tractable in the parameter  $k$ , likewise its variations. More specifically, there exists an FPT guess and check protocol for it with a witness size function  $s(k) = \binom{k}{2} \cdot \log k$  and a witness checker having runtime  $O(w \cdot k^2 \cdot |E|^w \cdot |V|^w)$ .

**Proof.** We first consider the case  $w = 1$ , i.e. the LONGEST PATH problem. Afterwards we will see that the algorithm is generalizable to the BANDWIDTH-w-PATH problem for  $w > 1$ . We state an FPT guess and check protocol for LONGEST PATH with the witness size function  $s(k) = \binom{k}{2} \cdot \log k$  and a witness checker with runtime  $O(k^2 \cdot |E| \cdot |V|)$ .

Let a digraph  $G$  with  $n$  vertices be given. We want to find out whether the graph contains a simple path  $p = (v_1, \dots, v_{k+1})$  of length  $k$ . We will work with *witnesses*. The intention of a witness is to tell the algorithm in the moment when it is trying to build an initial segment  $(v_1, \dots, v_i)$  of the simple path of length  $k$  which are the future vertices  $v_{i+1}, \dots, v_{k+1}$  of the simple path – so that the algorithm does not pick one of these future vertices as a part of the initial segment. Unfortunately,

$a_{2,1}$	$a_{2,2}$	$a_{2,3}$	$a_{2,4}$	= $a_2$ =	1	1	0	0
$a_{3,1}$	$a_{3,2}$	$a_{2,3}$		= $a_3$ =	1	2	0	
$a_{4,1}$	$a_{4,2}$			= $a_4$ =	2	0		
$a_{5,1}$				= $a_5$ =	0			

Figure 5: Witness table for a simple path of length 4

we cannot use the tuple  $(v_1, \dots, v_{k+1})$  as a witness, because that way we would have  $n^{k+1}$  potential witnesses, so that we would need at least  $(k+1) \log(n)$  bits to encode them, a number growing in  $n$ . But for the FPT guess and check protocol we need some witness size function  $s(k)$  only dependent on  $k$ .

We choose the following kind of witnesses. A *witness* for such a simple path of length  $k$  consists of  $k(k+1)/2 = \binom{k+1}{2}$  numbers  $a_{i,j} \in \{0, 1, \dots, k\}$ , for  $2 \leq i \leq k+1$  and  $j \in \{1, \dots, k-i+2\}$ . The witness can be visualized as a half-matrix  $a$ , see Figure 5. Let  $a_i$  for  $2 \leq i \leq k+1$  be the tuple  $(a_{i,1}, \dots, a_{i,k-i+2})$ . We can restrict the witnesses to have these properties:  $a_i$  contains only numbers  $\leq i-1$  and at least one 0. There is some redundancy, for example  $a_{k+1,1}$  will always be 0. Nevertheless, the order of magnitude of the witness size function  $s(k)$  does not seem to be improvable by these “little savings”.

For every witness  $a$  the main algorithm  $C$  does the following: In every of the  $k$  steps  $i = 2, 3, \dots, k+1$  it computes for every vertex  $v$  a value  $f_{a,i}(v)$ , defined further below, which is either a vertex or has the value **nil** (standing for “not existing”), and stores this function for use in the following steps. The following pseudo code shows the main structure of the algorithm.

Main algorithm C

Input: graph  $G$ , number  $k \leq |G|$ , and a witness  $a$

for every vertex  $v$  set  $f_{a,1}(v) := v$ ;

for  $i = 2, \dots, k+1$  do

for every vertex  $v$  in  $G$  do

compute  $f_{a,i}(v)$  and store it;

if  $i = k+1$  and  $f_{a,i}(v) \neq \mathbf{nil}$  ACCEPT and STOP;

REJECT and STOP;

The computation of the value  $f_{a,i}(v)$  – which is either **nil** or a vertex – is described in the pseudo code below. Assume w.l.o.g. that for each vertex there is a list of incoming edges (ending with the **nil** list element) in which the edges appear according to the order on the vertices. As a useful

abbreviation let  $f_{a,i}^d(v)$  for a vertex  $v$  and  $d$  with  $1 \leq d \leq i + 1$  be defined via

$$f_{a,i}^1(v) := v, \quad f_{a,i}^2(v) := f_{a,i}(v), \quad \text{and} \quad f_{a,i}^{d+1}(v) := f_{a,i-1}^d(f_{a,i}(v))$$

with this value being **nil** in case  $f_{a,i}(v)$  or  $f_{a,i-1}^d(f_{a,i}(v))$  equals **nil**. Intuitively,  $f_{a,i}^d(v)$  follows – starting in  $v$  – for growing  $d = 1, \dots, i + 1$  the “backward path” given by the  $f_{a,i-d}$ -functions, see Figure 6. The upper index  $d$  numbers the vertices of this path, and the witness elements  $a_{i,j} \geq 0$  will refer to this numbering.

By easy induction on  $i$ , the following invariant will be guaranteed for every witness  $a$ , every  $i$  with  $2 \leq i \leq k + 1$ , and every vertex  $v$ :

(Inv1) If  $f_{a,i}(v) \neq \mathbf{nil}$  then the “backward path”  $(f_{a,i}^i(v), \dots, f_{a,i}^2(v), f_{a,i}^1(v))$  is a simple path of length  $i - 1$ .

#### Computing $f_{a,i}(v)$

```

Input:  $i, a$ , and  $v$ . Already computed:  $f_{a,1}, \dots, f_{a,i-1}$ .
set  $F := \{v\}$ ;
set  $j := 1$ ;
if there are no incoming edges for  $v$  set  $f_{a,i}(v) := \mathbf{nil}$  and STOP;
set  $e = (u, v)$  to be the first edge incoming to  $v$ ;
while  $e \neq \mathbf{nil}$  do
  if  $f_{a,i-1}(u) \neq \mathbf{nil}$  and none of the vertices  $f_{a,i-1}^1(u), f_{a,i-1}^2(u), \dots, f_{a,i-1}^i(u)$  is in  $F$  do
    set  $c := a_{i,j}$ ;
    if  $c = 0$ 
      set  $f_{a,i}(v) := u$  and STOP;
    otherwise
      set  $F := F \cup \{f_{a,i}^c(u)\}$ ;
      set  $j := j + 1$ ;
  set  $e = (u, v) := \text{next edge going into } v$ ;
set  $f_{a,i}(v) := \mathbf{nil}$  and STOP;

```

Verification of the main algorithm  $C$ : If the algorithm accepts then it has found for this witness  $a$  a vertex  $v$  such that  $f_{a,k+1}(v) \neq \mathbf{nil}$ . By invariant (Inv1), case  $i = k + 1$ , the backward path starting in  $v$  is a simple path of length  $k$ .

On the other hand assume that there is a simple path of length  $k$  in  $G$ . Let  $s = (s_1, \dots, s_{k+1})$  be the lexicographically smallest among them (largest weight on  $s_{k+1}$ , unlike, for example, with decimal numbers). With the knowledge of this path and its vertices we will construct a witness  $b$  such that the main algorithm will accept for witness  $b$ .

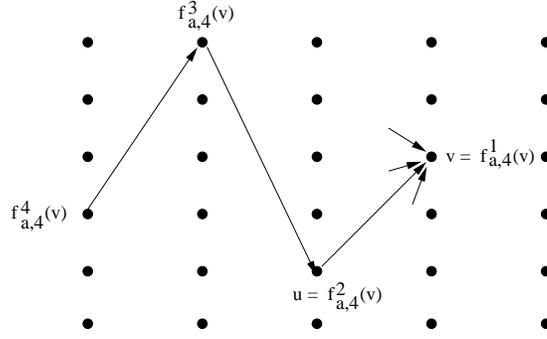


Figure 6: A “backward path”, starting in  $v$

### Constructing $b$

Input:  $s_1, \dots, s_{k+1}$ .

for every vertex  $v$  set  $f_{b_1,1}(v) = v$ ;

for  $i = 2$  to  $k + 1$  do

    set  $e = (u, s_i) :=$  first edge going into  $s_i$ ;

    set  $F = \{s_i\}$ ;

    set  $j := 1$ ;

    repeat

        while  $f_{b_{i-1},i-1}(u) = \mathbf{nil}$  or some of the vertices  $f_{b_{i-1},i-1}^1(u), \dots, f_{b_{i-1},i-1}^i(u)$  is in  $F$

            set  $e = (u, s_i) :=$  next edge going into  $s_i$ ;

        if there is a  $c \in \{1, \dots, i\}$  such that  $f_{b_{i-1},i-1}^c(u) \in \{s_{i+2}, \dots, s_{k+1}\}$

            set  $b_{i,j} := c$  for the smallest such  $c$ ;

            set  $F := F \cup \{f_{b_{i-1},i-1}^c(u)\}$ ;

            set  $j := j + 1$ ;

    until there is no such  $c$ ;

$b_{i,j} := 0$

    compute  $f_{b_i,i}(v)$  for all vertices  $v$ ;

The crucial invariant kept by this construction is the following:

(Inv2) For every  $i$  with  $2 \leq i \leq k + 1$  it holds:  $f_{b_i,i}(s_i) = s_{i-1}$ .

The invariant holds via induction on  $i$ : the construction of  $b_i$  prevents  $f_{b_i,i}(s_i)$  from choosing one of the vertices  $s_{i+1}, \dots, s_{k+1}$  which will be needed in the future but which would be – without

the witness – unknown at step  $i$ . Because there are at most  $k - i + 1$  such vertices the repeat loop will always terminate and, moreover, the part  $b_i$  of the witness has sufficient size. For every  $2 \leq i \leq k + 1$  it is guaranteed that the computation of  $f_{b,i}(s_i)$  will terminate, i.e. will be not-**nil**, because at least  $(s_{i-1}, s_i)$  is a suitable edge, and this will be the first suitable edge which  $f_{b,i}(s_i)$  will find, i.e.  $f_{b,i}(s_i) = s_{i-1}$ , because otherwise  $s = (s_1, \dots, s_{k+1})$  would not be lexicographically minimal.

Invariant (Inv2) implies for  $i = k + 1$  that the back path  $(f_{b,k+1}^{k+1}(s_{k+1}), \dots, f_{b,k+1}^2(s_{k+1}), f_{b,k+1}^1(s_{k+1}))$  at  $s_{k+1}$  equals  $s = (s_1, \dots, s_{k+1})$ , i.e. the main algorithm  $C$  will accept the input graph for this witness  $b$  via a non-**nil** value of  $f_{b,k+1}$  at vertex  $s_{k+1}$ . This finishes the correctness proof for the FPT guess and check protocol.

The running time of all  $f_{a_i}(v)$  for a fixed  $i$  is  $O(k \cdot |E|)$  (we ignore some  $\log(k)$  factors for the comparison algorithms). Therefore, the main algorithm  $C$  has runtime  $O(k^2 \cdot |V| \cdot |E|)$ . Representing all witnesses can be done with  $\binom{k}{2} \cdot \log k$  bits, i.e. the witness size function can be chosen this way (note that the diagonal of the half matrix does not need to be stored – it can be assumed to consist of 0's). This finishes the proof that an FPT guess and check protocol exists for LONGEST PATH.

Cases  $w > 1$ . We first do a graph transformation. From the given graph  $G$  construct the following graph  $G'$ : Consider all  $w$ -tuples  $(v_1, \dots, v_w)$  of vertices of  $G$ . Make such a tuple a vertex of  $G'$  if the tuple represents a directed  $w$ -clique in  $G$ , i.e.  $(v_i, v_j)$  is an edge in  $G$  for  $1 \leq i < j \leq w$ . The edges in  $G'$  are defined to consist of the pairs of such  $w$ -cliques of the special form  $((v_1, \dots, v_w), (v_2, \dots, v_w, v_{w+1}))$  such that also  $(v_1, v_{w+1})$  is an edge in  $G$ . We have the property:  $G$  contains a simple  $w$ -path of length  $k$  iff  $G'$  contains a 1-path of length  $k$ . The witness checker consists therefore of this graph transformation and subsequently the checking algorithm  $C$  for  $w = 1$  running on  $G'$ . In total the checking takes  $O(w \cdot |V|^w \cdot |E|^w)$  time, the first  $w$  stems from a slightly higher comparison time for tuples. The witnesses size function does not change.

Variants: For the vertex disjoint case with  $w > 1$  it is not enough to do the graph transformation, one has to go inside the checking algorithm  $C$  and maintain the vertex lists appropriately. **q.e.d.**

It should be mentioned that, when given  $k$  as a constant, the problem whether a given graph has a  $(w, k)$ -path does not seem to be fixed-parameter tractable in the parameter  $w$  because the W[1]-complete CLIQUE problem is obviously reducible to it, see for example [CCDF95] for the definition of W[1].

## 4 Conclusions and Open Questions

We introduced for every  $w \geq 1$  the NP-complete problem BANDWIDTH- $w$ -PATH and showed that it is fixed-parameter tractable in the length parameter  $k$  by presenting an FPT guess and check protocol for it, according to the characterization of Cai et al. [CCDF95].

As an open problem we suggest to study whether the witness size function, especially for the case LONGEST PATH, can be improved from the quasi-quadratic function  $\binom{k}{2} \log k$  to some quasi-linear function, for example by the methods of Monien [Mo85] or Alon, Yuster & Zwick [AYZ95].

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